INDEX

(A^TA) invertible and A nonsingular	Corollary 6.53, p. 489
(best) least-squares solution	Definition 6.47, p. 477
(m x n) linear system	Definition 2.4 and (2.5), p. 79
(m x n) matrix	Definition 1.1, p. 16
"is defined to be"	Introduction, p. 9
A nonsingular and (A^TA) invertible	Corollary 6.53, p. 489
addition of matrices	Definition 1.3, p. 18
algebraic multiplicity	Definition 8.30, p. 719
angles between vectors	(APP4.2) or (APP4.3), p. 777
augmented matrix	Definitions 2.14, p. 96
bad vs good equivalences	Theorem 4.58, pp. 341--347
basis	Definition 4.30, p. 286
basis and linear independence	4.53 and Theorem 4.56, pp. 329, pp. 332--333
basis and rank	Theorem 4.56, pp. 332--333
basis and spanning	4.51 and Theorem 4.56, pp. 326, 332--333
basis for null space	4.33, pp. 291--293
basis for span	4.35, pp. 297--298
best approximation	Terminology 6.15, p. 413
best approximation is projection	Theorem 6.14, p. 412
bivariate data	6.60, pp. 509--510
Cauchy-Schwarz inequality	6.26, p. 428
characteristic polynomial $c_A(t)$	Definition 8.7, p. 656
characteristic polynomials and eigenvalues	Theorem 8.8, p. 656
characteristic polynomials for similar matrices	Proposition 8.28, p. 713
closed form for powers of matrices	pp. 639 and 643
coefficient matrix	Definitions 2.14, p. 96
column n-vector	Definitions 1.8, p. 23
column space (of matrix)	p. 261
commuting and symmetric matrices	Proposition 3.14, p. 142
component	Definitions 1.17, p. 35
component in direction of vector	Definition 6.19, p. 418
consistency and rank	3.28, p. 166
consistent linear system	Definition 2.8, p. 81
coplanar	Definition 6.78, p. 542
cross product	Definition 6.69, p. 530
cross product direction	p. 553
cross product not commuting	Proposition 6.71, p. 533
cross product properties	Theorem 6.81, p. 545
cube C_n	5.1, p. 356
det = determinant	Definintion 5.5, pp. 366-367 and Proposition 5.7, p. 371
det and inverse	Theorem 5.12, p. 378
det and rank	Proposition 5.13, pp. 381--382
det properties	5.10, pp. 373--375
diagonal matrices commute	Proposition 3.13, pp. 140--141

diagonal matrix	Definition 3.3, p. 134
diagonal matrix terminology	Terminology 8.18, p. 687
diagonal of square matrix	Definition 3.1, p. 133
diagonalizability	Theorem 8.32, pp. 721--722
diagonalizable (matrix)	Definition 8.23, p. 693
diagonalizable and distinct eigenvalues	Theorem 8.34, p. 727
diagonalizable and symmetric matrices	Theorem 8.34, p. 727
diagonalization	Definition 8.23, pp. 693--694
diagonalized matrix powers	Theorem 8.19, pp. 687--688
diagonalizing: how to	8.25 pp. 696--697
difference equations	Definition 1.24, pp. 50--51
dim = dimension (of vector space)	Definition 4.39, p. 307
dim of null space and dim of range space	Corollary 4.50, p. 320
dim of range space and dim of null space	Corollary 4.50, p. 320
dim(range space) and rank	Corollary 4.43, p. 313
dim(span) and rank	Theorem 4.41, p. 310
directed line segment	Definitions 1.20, pp. 38--39
distinct eigenvalues implies diagonalizable	Theorem 8.34, p. 727
distributive law	pp. 769--770
dot product	Definitions 6.6 and 6.8, pp. 403--404
dot product and transpose	Proposition 6.48, p. 479
dot product properties	6.12, pp. 408--409
E Pluribus Unum	Introduction, p. 3
echelon form	Definition 2.20, p. 104
effects of elementary operations on det	5.8, p. 372
eigenspace	Definition 8.3, p. 650
eigenspace and null space	Theorem 8.5, p. 652
eigenvalue	Definition 8.1, p. 647
eigenvalues and characteristic polynomials	Theorem 8.8, p. 656
eigenvector	Definition 8.1, p. 647
eigenvectors and exponentials of matrices	Remarks APP2.7, p. 764
eigenvectors and powers of matrices	Theorem 8.14, p. 666
elementary matrices	Definitions 3.52, pp. 224--227
elementary operations	Definition 2.24, p. 109
equilibrium	Definition 8.10, p. 659
equivalent linear systems	Definition 2.11, p. 90
Euler's formula	p. 750
exponential of matrix	pp. 759--760
exponential of matrix and eigenvectors	Remark APP2.7, p. 764
Fibonacci numbers as difference equation	pp. 635--636
Fibonacci numbers defined	Definition 7.25, pp. 632--634
Fibonacci numbers population model	Example 7.24, pp. 629--632
Fibonacci numbers, closed form	Example 8.17, pp. 676--682
fixed point	Definition 8.10, p. 659
fixed points and Markov matrices	Theorem 8.11 and Remarks 8.13, pp. 661 and 664--665
foxes and rabbits	Examples 1.25(4), pp. 57--63
foxes and rabbits	Introduction, pp. 4--7

foxes and rabbits solved	Examples 8.37 and 8.38, pp. 729--746
foxes and rabbits, matrix construction	Examples 7.22(b), pp. 616--619
free variables	Definitions 2.13, p. 93
free variables and number of solutions	p. 152
free variables intuition, corrected	3.28, p. 166
free variables intuition, false	Intuition 3.23, pp. 156--159
function	Definition 7.1, p. 561
Gauss-Jordan elimination	2.29, p. 112
geometric multiplicity	Definition 8.30, p. 718
global method for solving difference equations	8.20, p. 689
golden ratio	pp. 683--684
golden rectangle	pp. 683--684
good vs bad equivalences	Theorem 4.58, pp. 341--347
Gram-Schmidt	6.44, p. 465
History	Introduction, pp. 2--3
homogeneous linear system	Definitions 3.16 and (3.17), p. 146
homogeneous nontrivial solutions	p. 152
how to diagonalize	8.25, pp. 696--697
hypotenuse of right triangle	p. 766
I	Definitions 3.5, pp. 135--136
identity matrix	Definitions 3.5, pp. 135--136
identity matrix properties	Proposition 3.6, p. 136
inconsistent linear system	Definition 2.8, p. 81
initial point	Definitions 1.20, pp. 38--39
initial state of difference equation	p. 70
inner product	Definitions 6.6 and 6.8, pp. 403--404
inverse (of a matrix)	Definitions 3.45, p. 210
inverse and det	Theorem 5.12, p. 378
inverse and linear systems	Theorem 3.47, p. 215
inverse calculation	3.49, p. 218
invertible (matrix)	Definitions 3.45, p. 210
least-squares approximating line	Definition 6.61 and Theorem 6.63, pp. 511 and 515
least-squares approximating model	Theorem 6.65, pp. 521--522
least-squares approximation	Terminology 6.15, p. 413
least-squares error	Definition 6.58, pp. 496--497
least-squares solutions and normal equations	Theorem 6.55, pp. 490--491
least-squares solutions when A nonsingular	Corollary 6.56, p, 494
legs of right triangle	p. 766
length (of vector)	Definition 6.1, Remarks 6.3, pp. 393--395
line	Definition 6.84
linear combinations	Definition 4.1, pp. 231--232
linear combinations and linear systems	Theorem 4.4, p. 242
linear combinations and rank	Theorem 4.4, p. 242
linear dependence and nontrivial linear combination	Proposition 4.23, p. 270
linear dependence and rank	Theorem 4.21, p. 267
linear dependence and unnecessary vectors	Theorem 4.28, p. 284

linear equation	Definition 2.1, p. 77
linear independence and basis	4.53 and Theorem 4.56, pp. 329, pp. 332--333
linear system	Definition 2.2, p. 78
linear systems and inverse	Theorem 3.47, p. 215
linear systems and linear combinations	Theorem 4.4, p. 242
linear systems and row equivalences	Theorem 2.27, p. 111
linear transformation	Definition 7.3, p. 566
linear transformations and matrices	Theorem 7.8, p. 572
linearly dependent	Definition 4.19, p. 266
linearly dependent columns and singularity	Theorem 4.25, p. 272
linearly independent	Definition 4.19, p. 266
local method for solving difference equations	8.15, pp. 667--668
magnification factor	5.1, p. 360
magnitude (of vector)	Definition 6.1, Remarks 6.3, pp. 393--395
Markov matrices and fixed points	Theorem 8.11 and Remarks 8.13, pp. 661 and 664--665
Markov matrix and process	Definitions 1.26, p. 68
matrices and linear transformations	Theorem 7.8, p. 572
matrix	Definition 1.1, p. 15
matrix addition	Definition 1.3, p. 18
matrix form of linear system	Definitions 2.14 and (2.15), pp. 94--95
matrix form, homogeneous linear system	Definitions 3.16 and (3.17), p. 146
matrix multiplication	Definitions 1.10 and 1.12, pp. 24, 26, and 27
matrix operations properties	1.15, pp. 31--32
matrix that is not diagonalizable	Example 8.29, pp. 715--716
matrix times standard basis	Lemma 7.10, p. 574
Moonorgs	Examples 1.25(5), pp. 63--67
Moonorgs, matrix construction	Examples 7.22 , pp. 619--623
multiplication of matrices	Definitions 1.10 and 1.12, pp. 24, 26, and 27
multiplicity, algebraic	Definition 8.30, p. 719
multiplicity, geometric	Definition 8.30, p. 718
natural numbers	Introduction, p. 10
nontrivial linear combinations and linear dependence	Proposition 4.23, p. 270
nontrivial solutions	3.33, p. 183
norm (of vector)	Definition 6.1, Remarks 6.3, pp. 393--395
normal equations	6.54, p. 490
normal equations and least-squares solutions	Theorem 6.55, pp. 490--491
not diagonalizable	Example 8.29, pp. 715--716
null space	Definition 3.35, p. 188
null space and eigenspace	Theorem 8.5, p. 652
null space basis	4.33, pp. 291--293
null space of (A^TA)	Corollary 6.52, p. 488
nullity and rank	Theorem 4.46, p. 317
nullity (of a matrix)	Definition 4.44, p. 314
nullity and number of free variables	Theorem 4.45, p. 315
number of free variables and nullity	Theorem 4.45, p. 315

number of free variables and rank	3.28, p. 166
number of solutions and free variables	p. 152
number of solutions illustrated	Remark 2.10, p. 90
number of solutions of linear system	Theorem 3.20, pp. 150--153
number of vectors in bases	Theorem 4.37, p. 306
n-vector	Definitions 1.17, p. 34
order of square matrix	5.1, p. 354
orthogonal	Definition 6.10, p. 406
orthogonal advantage (1): Pythagorean	6.33, p. 441
orthogonal advantage (2): linear combinations	6.36, p. 447
orthogonal advantage (3): projections	6.40, p. 456
orthogonal bases of eigenvectors and symmetry	Remark 8.36, p. 729
orthogonal basis	Definition 6.32, p. 439
orthogonal complement	Definition 6.49, pp. 479--480
orthogonal complement properties	Theorem 6.51, p. 483--484
orthogonal implies independence	Theorem 6.31, p. 436
orthogonal projection	Definition 6.13, pp. 410--411
orthogonal set	Definition 6.29, p. 434
orthogonal terminology	Terminology 6.5, p. 400
orthonormal set	Definition 6.43, p. 462
parallel (vectors)	Definitions 6.22, pp. 423--424
parallelepiped	Definition 6.75 and Proposition 6.76, pp. 539--541
parallelogram formed by two vectors	5.1, p. 357
pasting of matrices	Terminology 1.6, pp. 21--23
picture of vector operations	p. 45
point in opposite direction	Definitions 6.22, pp. 423--424
point in same direction	Definitions 6.22, pp. 423--424
popular vector spaces	4.17, pp. 260--261
powers of diagonalized matrix	Theorem 8.19, pp. 687--688
powers of matrices and eigenvectors	Theorem 8.14, p. 666
powers of matrices, closed form	pp. 639 and 643
powers of square matrix	Definitions 1.28, p. 71
prerequisites	Introduction, p. 8
projection	Definition 6.13, pp. 410--411
projection is best approximation	Theorem 6.14, p. 412
projection onto vector	(6.17) and Definition 6.16, pp. 415--416
projection onto vector formula	Theorem 6.18, p. 418
Pythagorean theorem	pp. 765--769
R^n	Definitions 1.17, p. 35
rabbits and foxes	Examples 1.25(4), pp. 57--63
rabbits and foxes	Introduction, pp. 4--7
rabbits and foxes solved	Examples 8.37 and 8.38, pp. 729--746
rabbits and foxes, matrix construction	Examples 7.22(b), pp, 616--619
radians	p. 749
range space	Definitions 3.41 and (3.42) and (3.43), pp. 199-203
range space and span	Theorem 4.15, p. 258

rank (of a matrix)	Definition 3.26, pp. 162--163
rank and basis	Theorem 4.56, pp. 332--333
rank and consistency	3.28, p. 166
rank and det	Proposition 5.13, pp. 381--382
rank and dim(range space)	Corollary 4.43, p. 313
rank and dim(span)	Theorem 4.41, p. 310
rank and linear combinations	Theorem 4.4, p. 242
rank and linear dependence	Theorem 4.21, p. 267
rank and nullity	Theorem 4.46, p. 317
rank and number of free variables	3.28, p. 166
rank and singularity	Theorem 4.25, p. 272
rank and unique solutions	Theorem 3.39, p. 194
rank properties	3.30, p. 173
real numbers	Introduction, p. 11
reduced echelon form	Definition 2.22, p. 107
reflection	7.16 and 7.17, pp. 605--607
representation of vector by directed line segment	Definitions 1.20, p. 40
right-hand rule	pp. 552--553
rotation matrices	p. 752
row equivalence and linear systems	Theorem 2.27, p. 111
row equivalent (matrix)	Definition 2.26, p. 110
row n-vector	Definitions 1.8, p. 23
row space (of matrix)	p. 261
scalar multiplication of matrices	Definition 1.3, p. 18
scalar product	Definitions 6.6 and 6.8, pp. 403--404
scalar triple product	Definition 6.72 and Proposition 6.74, pp. 534 and 537
scalars	Introduction, p. 12
similar matrices	Definition 8.22, p. 693
similarity and characteristic polynomials	Proposition 8.28, p. 713
simple eigenvalue	Chapter VIII homework
singular (matrix)	Definition 3.38, p. 193
singular matrix and unique solutions	Theorem 3.39, p. 194
singularity and linearly dependent columns	Theorem 4.25, p. 272
singularity and rank	Theorem 4.25, p. 272
solution of linear system	Definition 2.6, p. 80
solution of systems of constant-coefficient differential equations	Theorem APP2.3 and Corollary APP2.5, pp. 759--760
solutions in terms of homogeneous solutions	Theorem 3.18, p. 148
solutions of difference equations	Theorem 1.29, p. 72
span	Definitions 4.11, pp. 251--252
span and range space	Theorem 4.15, p. 258
span basis	4.35, pp. 297--298
spanning and basis	4.51 and Theorem 4.56, pp. 326, 332--333
square corner	p. 390
square matrix	Definitions 1.28, p. 71
stable point	Definition 8.10, p. 659
standard basis	Definition 4.32, pp. 288--289

standard matrix	Definition 7.6, p. 570
standard matrix for 45 degree rotation	7.12, pp. 587--593
standard matrix for 90 degree rotation	Examples 7.11(2), p. 578
standard matrix for projection	7.13 and (7.14), pp. 595--597
standard matrix for reflection	Proposition 7.18, p. 607
standard matrix for rotation	p. 752
steady state	Definition 8.10, p. 659
submatrix	Definitions 5.3, p. 364
subspaces of R^2	Proposition 4.10, p. 250
sum of angles	APP1.1, p. 750
symmetic implies diagonalizable	Theorem 8.34, p. 727
symmetric matrices and commuting	Proposition 3.14, p. 142
symmetric matrix	Definition 3.10, p. 139
symmetry and orthogonal bases of eigenvectors	Remark 8.36, p. 729
systems of constant-coefficient differential equations	(APP2.1) and (APP2.2), pp. 756--758
terminal point	Definitions 1.20, pp. 38--39
too many vectors implies linear dependence	Corollary 4.27, p. 281
transpose (of a matrix)	Definition 3.7, p. 137
transpose and dot product	Proposition 6.48, p. 479
transpose properties	3.9, p. 138
triangle inequality	6.28, p. 431
trivial solution	Definitions 3.16, p. 147
trivial vector	Definitions 3.16, p. 147
unique solutions	3.33, p. 183
unique solutions and rank	Theorem 3.39, p. 194
unique solutions and singular matrix	Theorem 3.39, p. 194
unit circle	p. 749
unit vector	Definition 6.4, p. 396
unnecessary vectors and linear dependence	Theorem 4.28, p. 284
vector form of linear system	Definitions 2.14 and (2.16), p. 96
vector operations picture	p. 45
vector space	Definition 4.8, p. 248
vector spaces, popular	4.17, pp. 260--261
vector subspace	Definition 4.8, p. 248
weighing self	Examples 6.59(c), pp. 502--505
zero vector	Definitions 3.16, p. 147